

# Naos Raptor 60A: Non-Isolated Power Modules 5 – 13.8Vdc input; 0.6Vdc to 5.0Vdc Output; 60A Output Current



# **RoHS Compliant**

# **Applications**

- Distributed power architectures
- Intermediate bus voltage applications
- Telecommunications equipment
- Servers and storage applications
- Networking equipment

#### **Features**

- Compliant to RoHS EU Directive 2002/95/EC (Z versions)
- Compatible in a Pb-free or SnPb wave-soldering environment (Z versions)
- Wide input voltage range (5Vdc-13.8Vdc)
- Output voltage programmable from 0.6Vdc to 5.0Vdc via external resistor
- Tunable Loop<sup>™</sup> to optimize dynamic output voltage response
- Fixed switching frequency
- Output overcurrent protection (non-latching)
- Over temperature protection
- Over voltage protection Hiccup Mode
- Remote On/Off
- Power Good Signal
- Small size:

65.5 mm x 31.8 mm x 11.6 mm

- (2.58 in. x 1.25 in. x 0.46 in.)
- Wide operating temperature range (0°C to 70°C)
- UL\* 60950 Recognized, CSA<sup>†</sup> C22.2 No. 60950-00 Certified, and VDE<sup>‡</sup> 0805 (EN60950-1 3<sup>rd</sup> edition) Licensed
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

### **Description**

The Naos Raptor 60A SIP power modules are non-isolated dc-dc converters in an industry standard package that can deliver up to 60A of output current with a full load efficiency of 92.1% at 3.3Vdc output voltage ( $V_{IN}$  = 12Vdc). These modules operate over a wide range of input voltage ( $V_{IN}$  = 5Vdc-13.8Vdc) and provide a precisely regulated output voltage from 0.6dc to 5.0Vdc, programmable via an external resistor. Features include remote On/Off, adjustable output voltage, over current, over temperature and over voltage protection. A new feature, the Tunable Loop<sup>TM</sup>, allows the user to optimize the dynamic response of the converter to match the load.

<sup>\*</sup> UL is a registered trademark of Underwriters Laboratories, Inc.

<sup>&</sup>lt;sup>†</sup> CSA is a registered trademark of Canadian Standards Association.

<sup>&</sup>lt;sup>‡</sup> VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
\*\* ISO is a registered trademark of the International Organization of Standards

# Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage					
Continuous	All	V <sub>IN</sub>	-0.3	15	Vdc
Operating Ambient Temperature	All	T <sub>A</sub>	0	70	°C
(see Thermal Considerations section)					
Storage Temperature	All	T <sub>stg</sub>	-55	125	°C

# **Electrical Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V <sub>IN</sub>	5	12.0	13.8	Vdc
Maximum Input Current	All	I <sub>IN,max</sub>			40	Adc
(V <sub>IN</sub> = V <sub>IN, min</sub> to V <sub>IN, max</sub> , I <sub>O</sub> =I <sub>O, max</sub> V <sub>O,set</sub> = 3.3Vdc)						
Input No Load Current						
$(V_{IN} = 9Vdc, I_0 = 0, module enabled)$	V <sub>O,set</sub> = 0.6 Vdc	I <sub>IN,No load</sub>		36		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	V <sub>O,set</sub> = 5.0Vdc	I <sub>IN,No load</sub>		86		mA
Input Stand-by Current	All	I <sub>IN,stand-by</sub>		1		mA
$(V_{IN} = 12Vdc, module disabled)$						
Inrush Transient	All	l <sup>2</sup> t			1	A <sup>2</sup> s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1µH source impedance; $V_{IN, min}$ to $V_{IN, max}$ , $I_0$ = $I_{Omax}$ ; See Test configuration section)	All			150		mAp-p
Input Ripple Rejection (120Hz)	All			50		dB

# Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Output Voltage Set-point						
$(V_{\text{IN}}\text{=}_{\text{IN, min}}, \text{ I}_{\text{O}}\text{=}\text{I}_{\text{O, max}}, \text{ T}_{\text{A}}\text{=}25^{\circ}\text{C}) \  \  V_{\text{o, SET}} \text{\geq} 1.2 V dc$	All	V <sub>O, set</sub>	-0.8		+0.8	% V <sub>O, set</sub>
V <sub>o, SET</sub> < 1.2Vdc	All	V <sub>O, set</sub>	-10		+10	mV
Output Voltage	All	V <sub>O, set</sub>	-1.1%		+1.1%	% V <sub>O, set</sub>
(Over all operating input voltage, resistive load,						
and temperature conditions until end of life) Adjustment Range	All	Vo	0.6		5.0	Vdc
Selected by an external resistor		۷O	0.0		5.0	Vuc
Output Regulation (for $V_0 \ge 2.5V$ )						
Input range1 (5V – 9V); range2 (9V – 13.8V)						
Line (Range1, range2)	All				0.3	% V <sub>O, set</sub>
Load $(I_0 = I_{0, min}$ to $I_{0, max}$ )	All				0.6	% V <sub>O, set</sub>
Line & Load	All				0.8	% V <sub>O, set</sub>
Output Regulation (for $V_0 < 2.5V$ )						,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
Input range1 (5V – 9V); range2 (9V – 13.8V)						
Line (Range1, range2)	All				9	mV
Load $(I_0=I_{0, min} \text{ to } I_{0, max})$	All				12	mV
Line & Load	All				15	mV
Output Ripple and Noise on nominal output						
$(V_{IN}=V_{IN, nom} \text{ and } I_O=I_{O, min} \text{ to } I_{O, max}, \text{ Cout} = 0\mu\text{F})$						
Peak-to-Peak (5Hz to 20MHz bandwidth)	Vo = 0.6V				30	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_0 = 1V$				30	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	Vo = 1.5V				40	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_0 = 2.5V$				40	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_0 = 3.3V$		_		60	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_0 = 5.0V$				60	mV <sub>pk-pk</sub>
External Capacitance <sup>1</sup>						тт у рк-рк
Without the Tunable Loop <sup>TM</sup>						
ESR $\geq 1 \text{ m}\Omega$	All	C <sub>O, max</sub>			1000	μF
With the Tunable Loop <sup>™</sup>		O, max			1000	μι
ESR $\geq 0.15 \text{ m}\Omega$	All	C <sub>O, max</sub>	0		2000	μF
$ESR \ge 10 \text{ m}\Omega$	All	C <sub>O, max</sub>	0		10000	μF
Output Current	All	I <sub>o</sub>	0		60	Adc
Output Current Limit Inception (Hiccup Mode )	All	I <sub>O, lim</sub>	103	130	180	% I <sub>o</sub>
Output Short-Circuit Current	All	I <sub>O, s/c</sub>	_	5	_	Adc
(V₀≤250mV) ( Hiccup Mode )		10, 310		-		
Efficiency	V <sub>O,set</sub> = 0.6Vdc	η		74.4		%
$V_{IN} = V_{IN, nom}, T_A = 25^{\circ}C$	$V_{O,set} = 1.2Vdc$	η		85.0		%
$I_0 = I_{0, \text{max}}, V_0 = V_{0, \text{set}}$	$V_{O,set} = 1.8Vdc$	η		88.6		%
5 5, Hida, 7 5 7 5, Set	$V_{O,set} = 2.5 V dc$	η		91.0		%
	$V_{O,set} = 3.3 V dc$	η		92.1		%
	$V_{O,set} = 5.0Vdc$ $V_{O,set} = 5.0Vdc$	η		93.5		%
Switching Frequency	All	f <sub>sw</sub>		333		/0 kHz
omining i requeriey	110	'SW		000		11112

<sup>1</sup> External capacitors may require using the new Tunable Loop<sup>™</sup> feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop<sup>™</sup> section for details.

# **General Specifications**

Parameter	Min	Тур	Max	Unit
Calculated MTBF (V <sub>IN</sub> =12V, V <sub>o</sub> =1.5Vdc, I <sub>o</sub> =60°, T <sub>A</sub> =40°C) Per Telcordia Issue 2, Method I Case 3		2,808,442		Hours
Weight		22 (0.78)		g (oz.)

# **Feature Specifications**

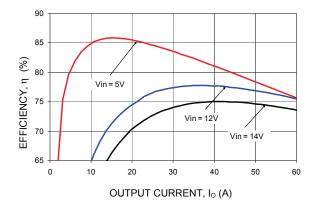
Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Enable Signal Interface $(V_{IN}=V_{IN,min} \text{ to } V_{IN,max}; \text{ open collector or equivalent,}$						
Signal referenced to GND)						
Logic High (Enable pin open – Module ON)						
Input High Current	All	Ін	0.5	—	3.3	mA
Input High Voltage	All	Vін	3.5	—	$V_{\text{in,max}}$	V
Logic Low (Module OFF)						
Input Low Current	All	lı∟	_	—	200	μA
Input Low Voltage	All	VIL	-0.3	—	1.2	V
PwGood (Power Good) Signal Interface Open Collector/Drain PwGood = High = Power Good PwGood = Low = Power Not Good						
Logic level low voltage, I <sub>sink</sub> = 4 mA			0		0.4	V
Logic level high voltage, I <sub>source</sub> = 2 mA			2.4		5.25	V
Sink Current, PwGood = low					4	mA
Source Current, PwGood = high					2	mA
Turn-On Delay and Rise Times $(V_{IN}=V_{IN, nom}, I_0=I_{0, max}, V_0$ to within ±1% of steady state)						
Case 1: Enable input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN, min}$ until $V_0 = 10\%$ of $V_{0, set}$ )	All	Tdelay			3	msec
Case 2: Input power is applied for at least one second and then the Enable input is enabled (delay from instant at which Enable is enabled until $V_0 = 10\%$ of $V_{0, set}$ )	All	Tdelay			1.2	msec
Output voltage Rise time (time for V $_0$ to rise from 10% of Vo, set to 90% of Vo, set)	All	Trise			3	msec
Output voltage overshoot $I_{O} = I_{O, max}; V_{IN, min} - V_{IN, max}, T_{A} = 25 \ ^{\circ}C$					0.5	% V <sub>O, set</sub>
Remote Sense Range	All		—	—	0.5	V
Over Temperature Protection	All	T <sub>ref</sub>		135		°C
(See Thermal Considerations section)						
Input Undervoltage Lockout						
Turn-on Threshold	All			4.5	4.8	Vdc
Turn-off Threshold	All			4.1	4.4	Vdc
Overvoltage Protection (Hiccup Mode)	All		120	125	130	V <sub>O, set</sub> , %

OUTPUT CURRENT,

### **Characteristic Curves**

The following figures provide typical characteristics for the Naos Raptor 60A module at 0.6Vout and at 25°C.



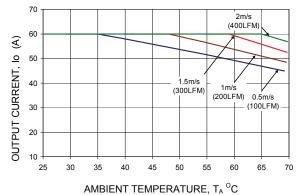


Figure 1. Converter Efficiency versus Output Current.

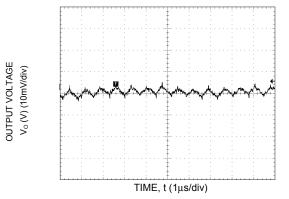


Figure 3. Typical output ripple and noise ( $V_{IN}$  = 12V,  $I_o$  =  $I_{o,max}$ ).

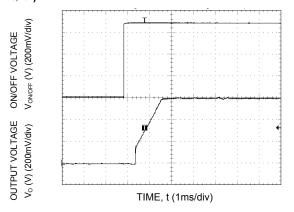


Figure 5. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 2. Derating Output Current versus Ambient Temperature and Airflow.

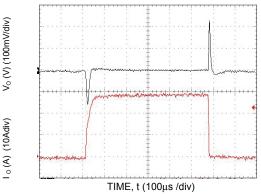


Figure 4. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{\text{IN}}\text{=}12V.$ 

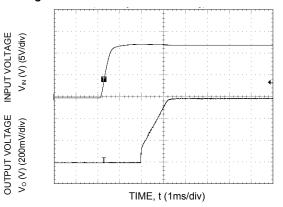


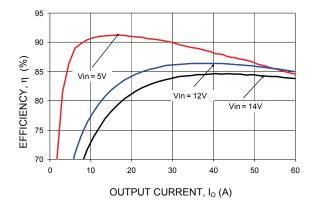
Figure 6. Typical Start-up Using Input Voltage (VIN = 12V, Io = Io,max).

INPUT VOLTAGE

**DUTPUT VOLTAGE** 

# **Characteristic Curves (continued)**

The following figures provide typical characteristics for the Naos Raptor 60A module at 1.2Vout and at 25°C.



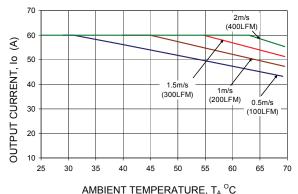
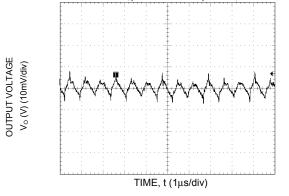
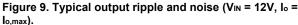


Figure 7. Converter Efficiency versus Output Current.





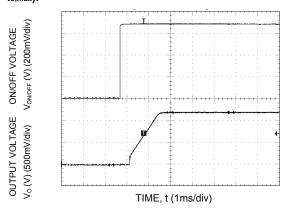


Figure 11. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 8. Derating Output Current versus Ambient Temperature and Airflow.

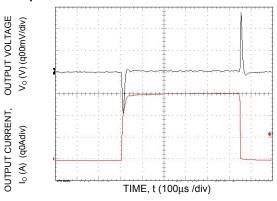


Figure 10. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN}$ =12V.

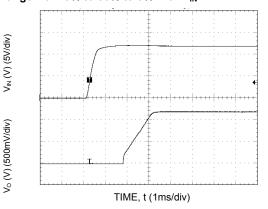
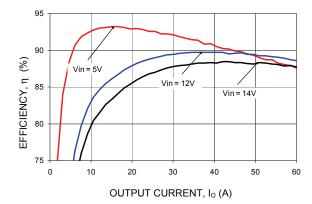


Figure 12. Typical Start-up Using Input Voltage (VIN = 12V,  $I_0 = I_{0,max}$ ).

OUTPUT CURRENT,

# **Characteristic Curves (continued)**

The following figures provide typical characteristics for the Naos Raptor 60A module at 1.8Vout and at 25°C.



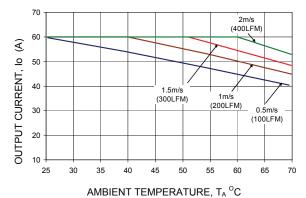


Figure 13. Converter Efficiency versus Output Current.

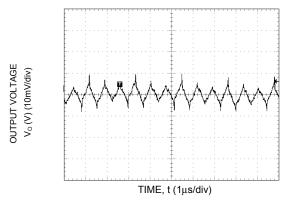


Figure 15. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

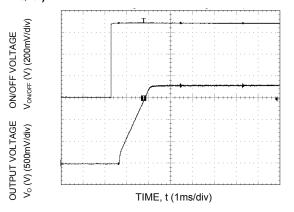


Figure 17. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 14. Derating Output Current versus Ambient Temperature and Airflow.

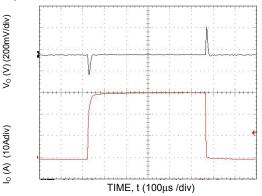


Figure 16. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN}$ =12V.

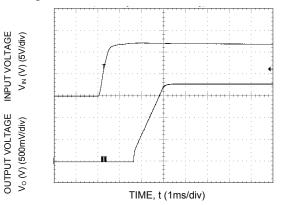


Figure 18. Typical Start-up Using Input Voltage (VIN = 12V, Io = Io,max).

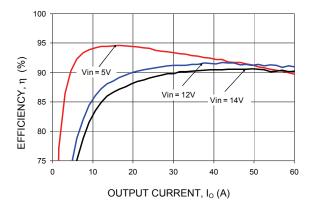
OUTPUT CURRENT,

INPUT VOLTAGE

OUTPUT VOLTAGE

# **Characteristic Curves (continued)**

The following figures provide typical characteristics for the Naos Raptor 60A module at 2.5Vout and at 25°C.



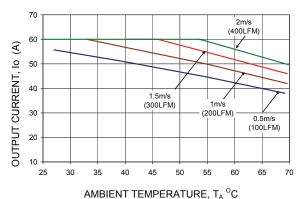
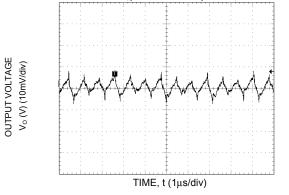
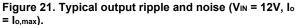


Figure 19. Converter Efficiency versus Output Current.





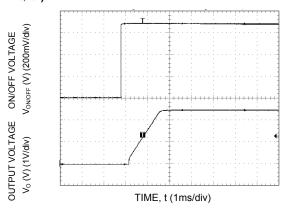
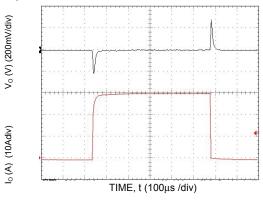
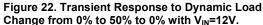


Figure 23. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 20. Derating Output Current versus Ambient Temperature and Airflow.





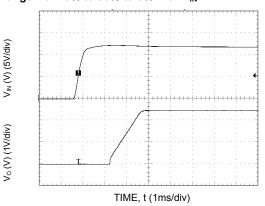
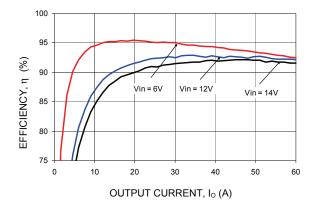


Figure 24. Typical Start-up Using Input Voltage (VIN = 12V, Io = Io,max).

OUTPUT CURRENT,

# **Characteristic Curves (continued)**

The following figures provide typical characteristics for the Naos Raptor 60A module at 3.3Vout and at 25°C.



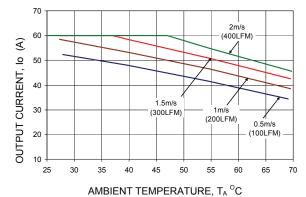


Figure 25. Converter Efficiency versus Output Current.

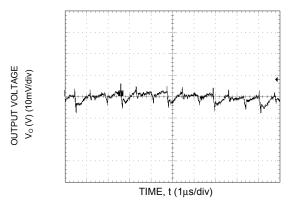


Figure 27. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

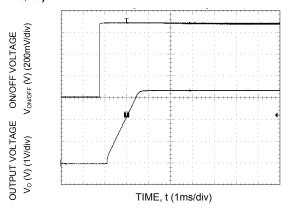


Figure 29. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 26. Derating Output Current versus Ambient Temperature and Airflow.

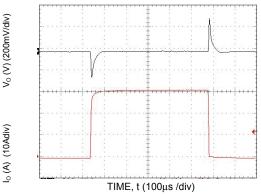


Figure 28. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN}$ =12V.

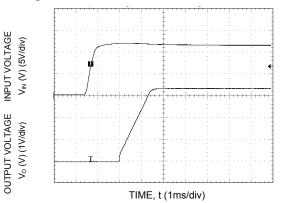


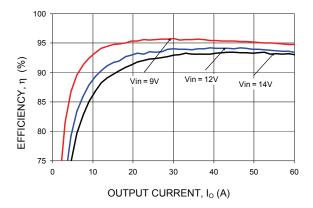
Figure 30. Typical Start-up Using Input Voltage (VIN = 12V, Io = Io,max).

# **Characteristic Curves (continued)**

The following figures provide typical characteristics for the Naos Raptor 60A module at 5Vout and at 25°C.

OUTPUT VOLTAGE

OUTPUT CURRENT,



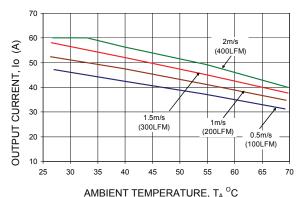


Figure 31. Converter Efficiency versus Output Current.

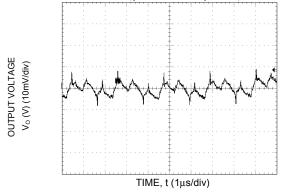


Figure 33. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

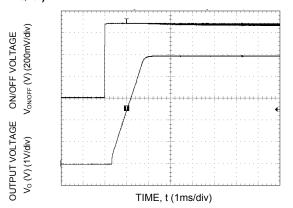


Figure 35. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 32. Derating Output Current versus Ambient Temperature and Airflow.

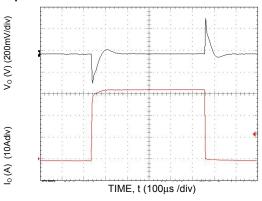


Figure 34. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN}$ =12V.

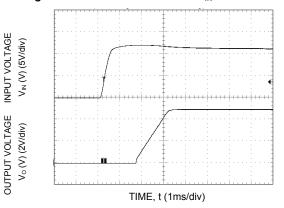
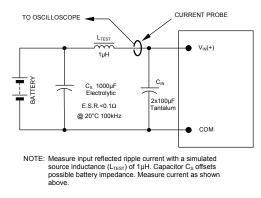
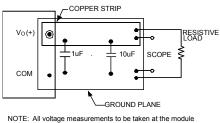


Figure 36. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{0,max}$ ).

# **Test Configurations**

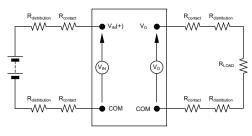


# Figure 37. Input Reflected Ripple Current Test Setup.



Kerkinger indeastrelements to be radiuse in the include terminals, as shown above. If sockets are used then Kelvin connections are required at the module terminals to avoid measurement errors due to socket contact resistance.





NOTE: All voltage measurements to be taken at the module terminals, as shown above. If sockets are used then Kelvin connections are required at the module terminals to avoid measurement errors due to socket contact resistance.

# Figure 39. Output Voltage and Efficiency Test Setup.

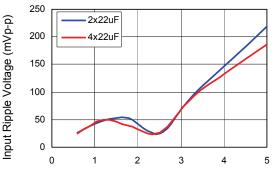
Efficiency 
$$\eta = \frac{V_{0.} I_{0}}{V_{IN} I_{IN}} \times 100 \%$$

#### **Design Considerations**

#### **Input Filtering**

The Naos Raptor 60A module should be connected to a low-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, low-ESR polymer and ceramic capacitors are recommended at the input of the module. Figure 40 shows the input ripple voltage for various output voltages at 60A of load current with  $2x22 \ \mu$ F or  $4x22 \ \mu$ F ceramic capacitors and an input of 12V.



Output Voltage (Vdc)

Figure 40. Input ripple voltage for various output voltages with  $2x22 \ \mu$ F or  $4x22 \ \mu$ F ceramic capacitors at the input (60A load). Input voltage is 12V.

#### **Output Filtering**

The Naos Raptor 60A modules are designed for low output ripple voltage and will meet the maximum output ripple specification with no external capacitors. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR ceramic and polymer are recommended to improve the dynamic response of the module. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable  $\text{Loop}^{\text{TM}}$  feature described later in this data sheet.

## **Safety Considerations**

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL 60950-1, CSA C22.2 No. 60950-1-03, and VDE 0850:2001-12 (EN60950-1) Licensed.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

An input fuse for the module is recommended. Due to the wide input voltage and output voltage ranges of the module, different fuse ratings are recommended as shown in Table 1. These are suggested "maximum" fuse ratings. However, for optimum circuit protection, the fuse value should not be any larger than required in the end application. As an option to using a fuse, no fuse is required, if the module is

- 1. powered by a power source with current limit protection set point less than the protection device value listed in Table 1, and
- 2. the module is evaluated in the end-use equipment.

Table 1.

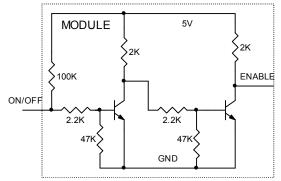
Input Voltage	Output Voltage (VDC)						
(VDC)	0.59 to 1.3	1.31 to 2.7	2.71 to 5.0				
10.1 to 14	25A	50A	80A				
6.51 to 10	40A	70A	100A				
5 to 6.5	40A	90A	100A				

# **Feature Descriptions**

#### Enable (Remote On/Off)

The Naos Raptor 60A power modules feature a Enable pin with positive logic for remote On/Off operation. If not using the Enable pin, leave the pin open (the module will be ON, except for the -49 option modules where leaving the pin open will cause the module to remain OFF). The Enable signal ( $V_{Enable}$ ) is referenced to ground.

During a Logic High on the Enable pin, the module remains ON. During Logic-Low, the module is turned OFF.



# Figure 41. Remote On/Off Implementation. The 100K resistor is absent in the -49 option modules.

#### **Overcurrent Protection**

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range. The typical average output current during hiccup is 10% of I<sub>o,max</sub>.

#### **Over Temperature Protection**

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of  $135^{\circ}$ C is exceeded at the thermal reference point T<sub>red</sub>. The thermal shutdown is not intended as a guarantee that the unit will survive temperatures beyond its rating. Once the unit goes into thermal shutdown, it will then wait to cool before attempting to restart.

#### Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

#### **Power Good**

The Naos Raptor 60A power modules provide a Power Good Status signal that indicates whether or not the power module is functioning properly.

PwGood is a power good signal implemented with an open-collector output to indicate that the output voltage is within the regulation limits of the power module. The PwGood signal will be de-asserted to a low state If any condition such as over-temperature, over-current, or over-voltage occurs which would result in the output voltage going out of range.

#### **Output Voltage Programming**

The output voltage of the Naos Raptor 60A module can be programmed to any voltage from 0.6Vdc to 5.0Vdc by connecting a resistor between the Trim + and Trim - pins of the module. Without an external resistor between Trim + and Trim - pins, the output of the module will be 0.6Vdc. To calculate the value of the trim resistor, *Rtrim* for a desired output voltage, use the following equation:

$$Rtrim = \frac{1.2}{(Vo - 0.6)} k\Omega$$

Rtrim is the external resistor in  $k\Omega$ 

Vo is the desired output voltage

Table 2 provides Rtrim values required for some common output voltages.

By using a  $\pm 0.1\%$  tolerance trim resistor with a TC of  $\pm 25$ ppm, a set point tolerance of  $\pm 0.8\%$  can be achieved as specified in the electrical specification. The POL Programming Tool available at www.lineagepower.com under the Design Tools section, helps determine the required trim resistor needed for a specific output voltage.

Note: Vin  $\geq$  180% of Vout at the module output pin.

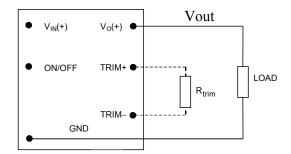


Figure 42. Circuit configuration for programming output voltage using an external resistor.

#### Table 2

V <sub>O, set</sub> (V)	Rtrim (Ω)
0.6	Open
1.0	3000
1.2	2000
1.5	1333
1.8	1000
2.5	632
3.3	444
5.0	273

#### **Monotonic Start-up and Shutdown**

The Naos Raptor 60A modules have monotonic startup and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

# **Feature Descriptions (continued)**

# Tunable Loop<sup>™</sup>

The Naos Raptor 60A modules have a new feature that optimizes transient response of the module called Tunable Loop<sup>TM</sup>. External capacitors are usually added to improve output voltage transient response due to load current changes. Sensitive loads may also require additional output capacitance to reduce output ripple and noise. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

To use the additional external capacitors in an optimal manner, the Tunable Loop<sup>TM</sup> feature allows the loop to be tuned externally by connecting a series R-C between the SENSE and TRIM pins of the module, as shown in Fig. 43. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module to match the filter network connected to the output of the module.

Recommended values of  $\mathsf{R}_{\mathsf{TUNE}}$  and  $\mathsf{C}_{\mathsf{TUNE}}$  are given in Tables 3 and 4. Table 3 lists recommended values of R<sub>TUNE</sub> and C<sub>TUNE</sub> in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 30A to 60A step change (50% of full load), with an input voltage of 12V. Table 4 shows the recommended values of R<sub>TUNE</sub> and C<sub>TUNE</sub> for different values of ceramic output capacitors up to 1880 µF, again for an input voltage of 12V. The value of R<sub>TUNE</sub> should never be lower than the values shown in Tables 3 and 4. Please contact your Lineage Power technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

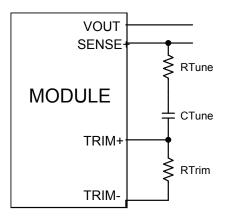


Figure. 43. Circuit diagram showing connection of  $R_{\text{TUME}}$  and  $C_{\text{TUNE}}$  to tune the control loop of the module.

Table 3. Recommended values of R <sub>TUNE</sub> and C <sub>TUNE</sub>
to obtain transient deviation of 2% of Vout for a
30A step load with Vin=12V.

Vout	5V	3.3V	2.5V	1.8V	1.2V	0.6V
Cext		6x47μF + 3x330μF Polymer			13x330µF Polymer	31x330µF Polymer
R <sub>TUNE</sub>	100	68	47	39	33	30
C <sub>TUNE</sub>	12nF	27nF	47nF	100nF	180nF	180nF
ΔV	100mV	66mV	50mV	36mV	24mV	12mV

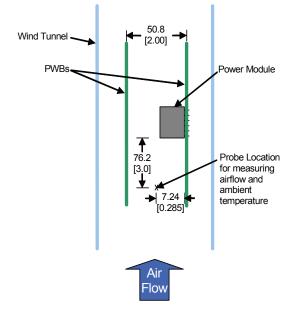
Table 4. General recommended values of of  $R_{TUNE}$  and  $C_{TUNE}$  for Vin=12V and various external ceramic capacitor combinations.

Cext 2x47µF		4x47μF 10x47μF		20x47µF	40x47µF	
R <sub>TUNE</sub>	100	75	47	33	30	
CTUNE	2700pF	4700pF	12nF	22nF	27nF	

# **Thermal Considerations**

Power modules operate in a variety of thermal environments; however sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test setup is shown in Figure 44. The derating data applies to airflow in either direction of the module's axis.



#### Figure 44. Thermal Test Set-up.

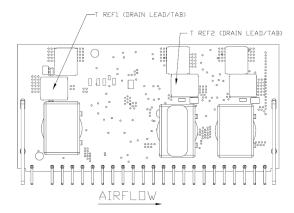


Figure 45. Temperature measurement locations  $T_{ref1}$  and  $T_{ref2}.$ 

The thermal reference points,  $T_{ref1}$  and  $T_{ref2}$  used in the specifications are shown in Figure 45. For reliable operation this temperatures should not exceed 120 °C. The output power of the module should not exceed the rated power of the module (Vo.set x Io.max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

#### **Heat Transfer via Convection**

Increased airflow over the module enhances the heat transfer via convection. Thermal derating curves showing the maximum output current that can be delivered at different local ambient temperatures ( $T_A$ ) for airflow conditions ranging from natural convection and up to 2m/s (400 ft./min) are shown in the Characteristics Curves section.

# Post solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to the *Board Mounted Power Modules: Soldering and Cleaning* Application Note.

# Through-Hole Lead-Free Soldering Information

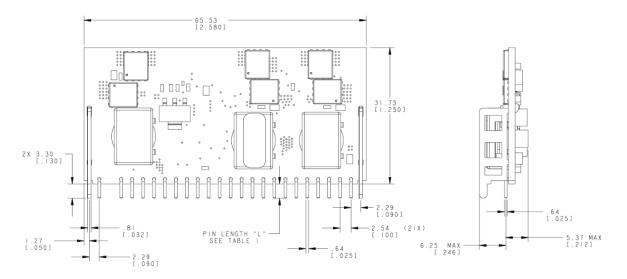
The RoHS-compliant through-hole products use the SAC (Sn/Aq/Cu) Pb-free solder and RoHS-compliant components. They are designed to be processed through single or dual wave soldering machines. The pins have an RoHS-compliant finish that is compatible with both Pb and Pb-free wave soldering processes. A maximum preheat rate of 3°C/s is suggested. The wave preheat process should be such that the temperature of the power module board is kept below 210°C. For Pb solder, the recommended pot temperature is 260°C, while the Pb-free solder pot is 270°C max. Not all RoHS-compliant through-hole products can be processed with paste-through-hole Pb or Pb-free reflow process. If additional information is needed, please consult with your Lineage Power representative for more details.

# **Mechanical Outline**

Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)



# L = $2.85 \pm 0.25$ [ $0.112 \pm 0.01$ ] L = $5.08 \pm 0.25$ [ $0.200 \pm 0.01$ ] 5 Option

# **Front View**

# Side View

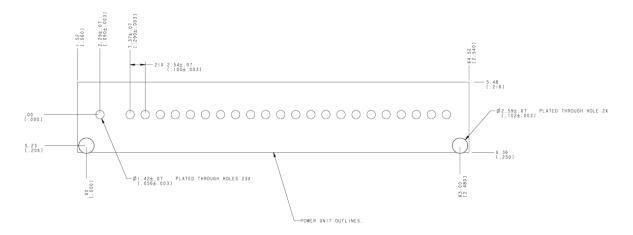
Pinout									
Pin	Function	Pin	Function	Pin	Function				
1	Trim +	9	Enable	18	V <sub>out</sub>				
2	No Pin	10	Sense -	19	GND				
3	GND	11	Sense +	20	V <sub>out</sub>				
4	PwGood	12	V <sub>in</sub>	21	GND				
5	Trim -	13	V <sub>in</sub>	22	V <sub>out</sub>				
6	Ishare	14	V <sub>in</sub>	23	GND				
7	GND	15	Vout	24	V <sub>out</sub>				
8	GND	16	V <sub>out</sub>	25	GND				
		17	GND	26	GND				

# **Recommended Pad Layout**

Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)



# **Ordering Information**

Please contact your Lineage Power Sales Representative for pricing, availability and optional features.

# Table 5. Device Codes

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Connector Type	Comcode
NSR060A0X43Z	5 – 13.8Vdc	0.6 - 5.0Vdc	60 A	Positive	SIP	CC109130936
NSR060A0X43-49Z*	5 – 13.8Vdc	0.6 - 5.0Vdc	60 A	Positive	SIP	CC109138236
NSR060A0X543-37Z*	5 – 13.8Vdc	0.6 - 5.0Vdc	60 A	Positive	SIP	CC109150942

Z refers to RoHS-compliant versions.

#### \* Special codes, consult factory before ordering

#### Table 6. Device Options

Option	Suffix
Long Pins 5.08 mm ± 0.25 mm [0.2 ± 0.010 in.]	5



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